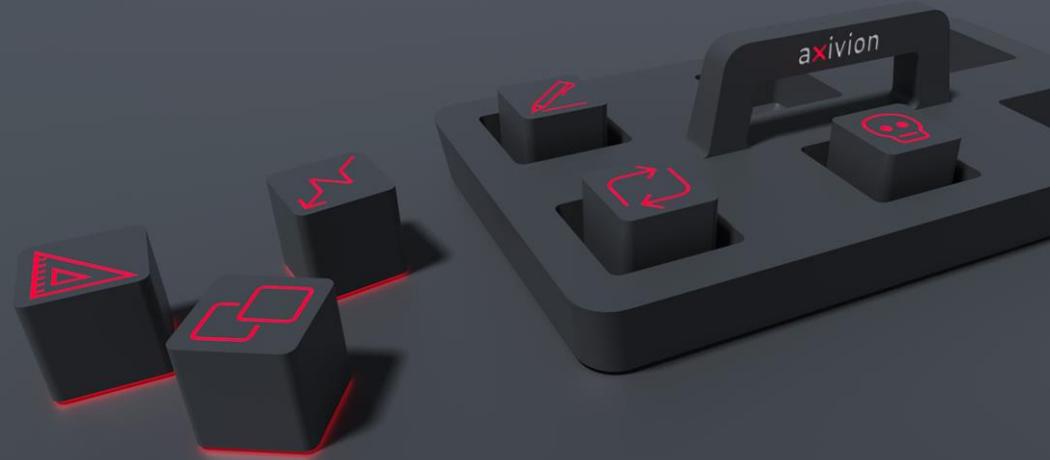




# Testing, Model Checking and Static Analysis

Dream Team or Rivals?



Sebastian Krings

Axivion GmbH

**axivion**  
stopping software erosion

“Software is eating  
the world.”

- Marc Andreessen

- Software used everywhere, from cars to trains to medical devices
- Software errors lead to damages, loss of equipment and have killed people
- Enormous financial losses due to software not even deemed safety-critical

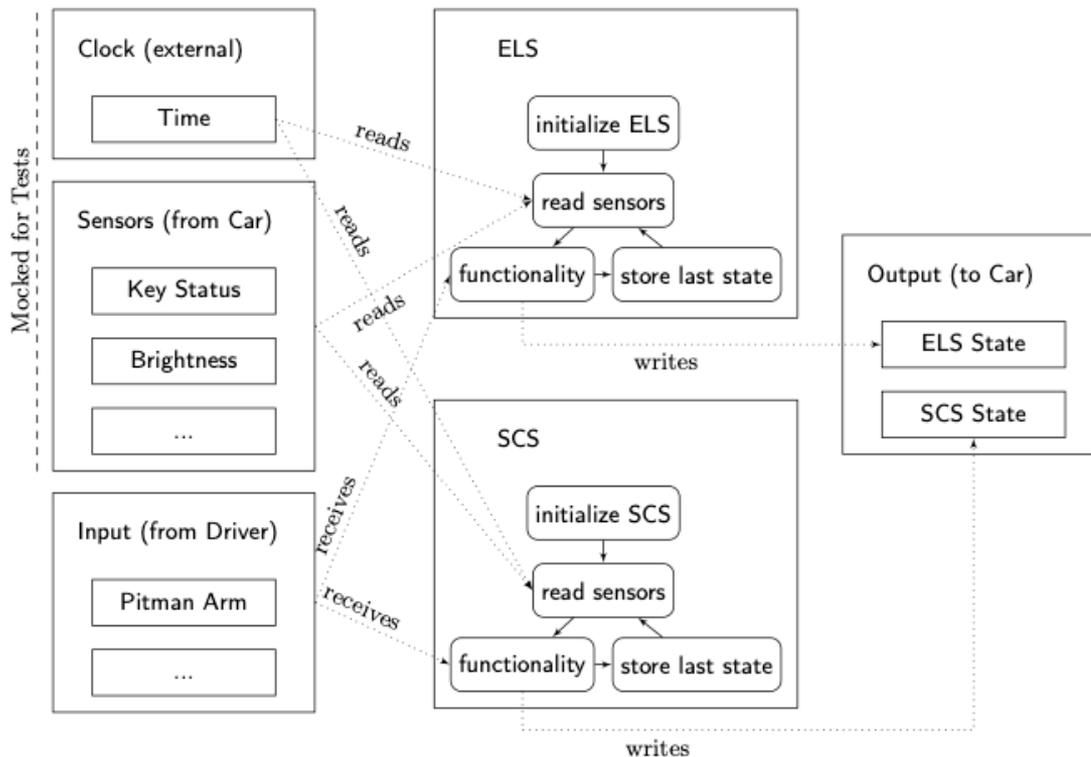


**We need to get software right.**

**Let's see how.**

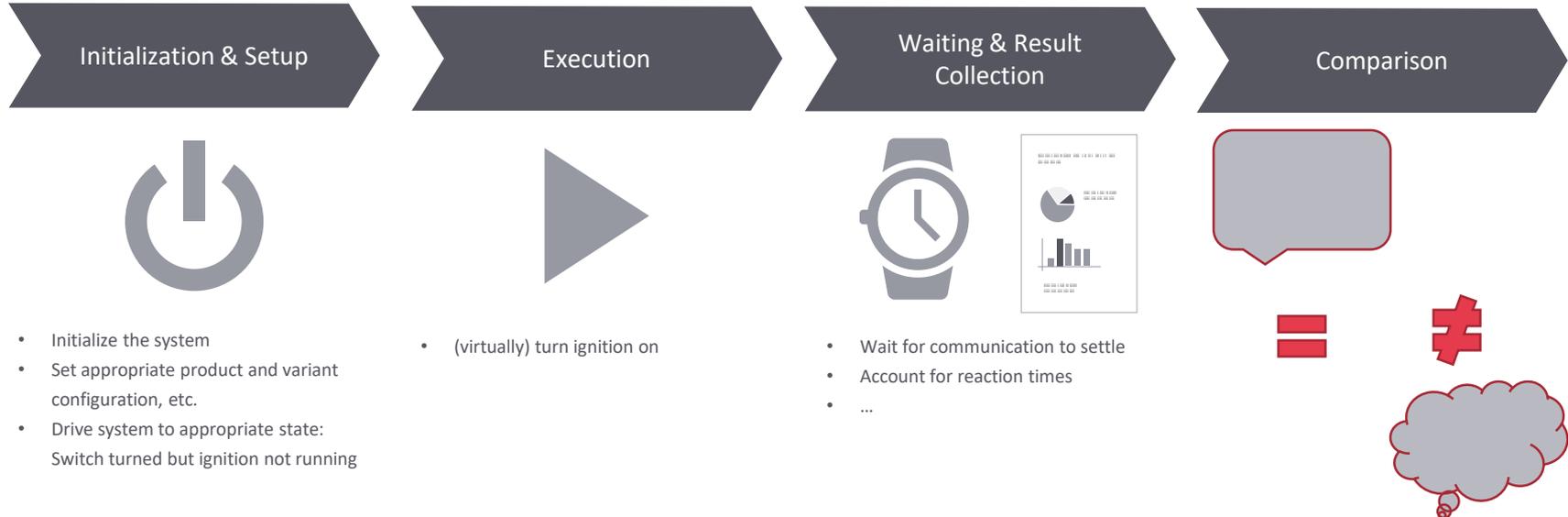
Images by Catalina Márquez under CC BY-SA 3.0 and ESA

System	Controls	Reads	Development
Adaptive Exterior Light System (ELS)	Head- and taillights <ul style="list-style-type: none"><li>• Brightness</li><li>• Illumination distance</li><li>• Curve lighting</li></ul>	<ul style="list-style-type: none"><li>• Driver input via actuators</li><li>• Sensors for Speed, etc.</li></ul>	<ul style="list-style-type: none"><li>• To be developed in C</li><li>• Following the MISRA C 2012 coding guidelines</li><li>• Obviously highly safety critical</li></ul>
Speed Control System (SCS)	Speed of vehicle <ul style="list-style-type: none"><li>• Acceleration</li><li>• Deceleration</li><li>• Emergency breaks</li></ul>		



- Broadly speaking: make the system under test execute a certain scenario and check if we like the outcome
- Many different kinds and ideas
  - White-, black- and grey-box testing
  - Unit, integration and system testing
  - Sanity- and smoke-testing
  - Manual and automated testing
  - Hardware-in-the-loop and mocking
  - ....

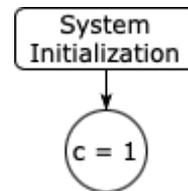
Requirement: If the ignition is 'On' and the light rotary switch is in the position 'On', then low beam headlights are activated.



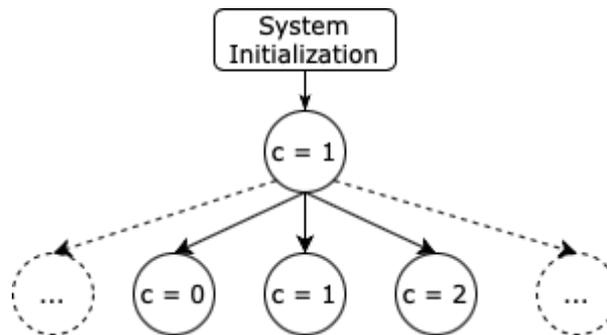
- Requirement is only partially tested
  - We have switch first, ignition second
  - But we are missing ignition first, switch second
- Needed to mock away the sensors
- No hope to ever test exhaustively
- Add some coverage metric
  - Statement, condition, MC/DC, ...

- Broadly speaking: explore all states the system might be in, check an invariant property for each
- Many different kinds and ideas:
  - Abstraction level
  - Explicit or symbolic states
- Consider expressiveness of underlying logic, i.e., what is the invariant allowed to talk about
  - State only
  - Path on which a state was reached
  - Past or future states

```
extern int some_value();  
int main {  
    int c = 1;  
    c += some_value();  
    ...  
}
```



```
extern int some_value();  
int main {  
    int c = 1;  
    c += some_value();  
    ...  
}
```



- Requirement: Whenever the low or high beam headlights are activated, the tail lights are activated, too.
- Translate into invariant
- Check using CBMC (for instance)

```
assert(implies(state.lowBeamLeft > 0,  
               state.tailLampLeft > 0 &&  
               state.tailLampRight > 0));
```

State 59 file light/light-impl.c line 242 function light\_do\_step thread 0

-----

ks=/\*enum\*/NoKeyInserted (00000000000000000000000000000000)

State 63 file light/light-impl.c line 242 function light\_do\_step thread 0

-----

ks=/\*enum\*/KeyInIgnitionOnPosition (00000000000000000000000000000010)

State 65 file light/light-impl.c line 244 function light\_do\_step thread 0

-----

engine\_on=FALSE (00000000)

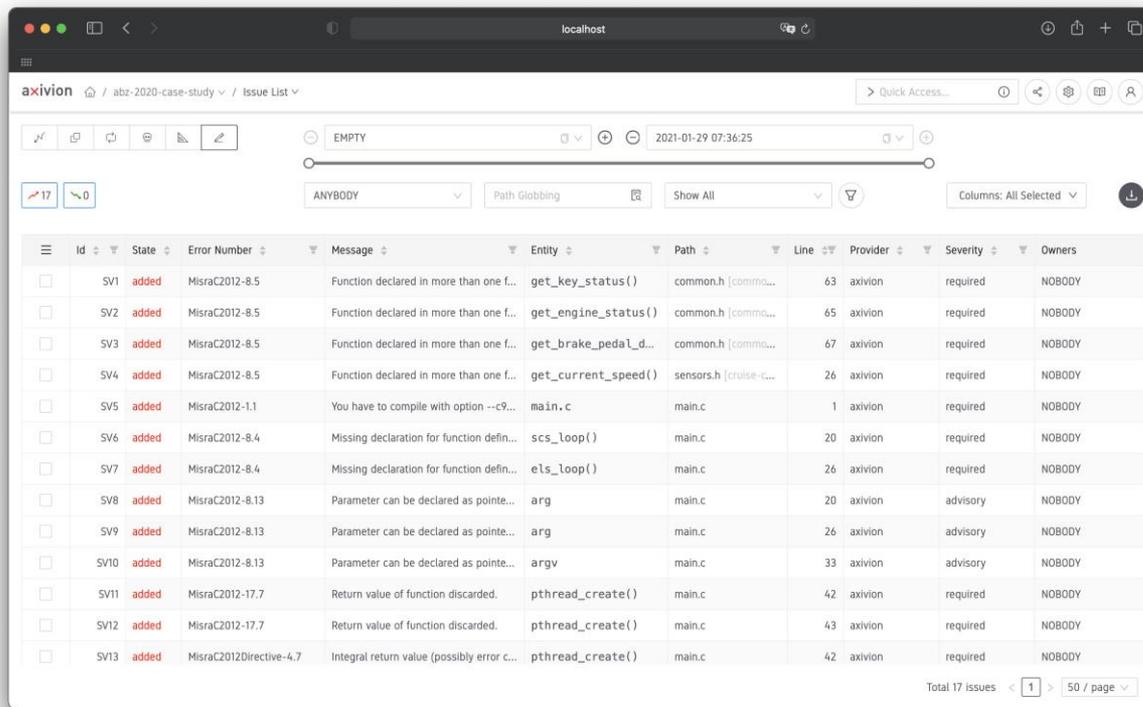
State 69 file light/light-impl.c line 244 function light\_do\_step thread 0

-----

engine\_on=TRUE (00000001)

- Combinatorial explosion!
- Checking industrial-scale systems often infeasible
- But checking the whole system is not needed to discover errors
- Techniques to increase applicability:
  - Symbolic techniques
  - Symmetry detection and avoidance
  - ...

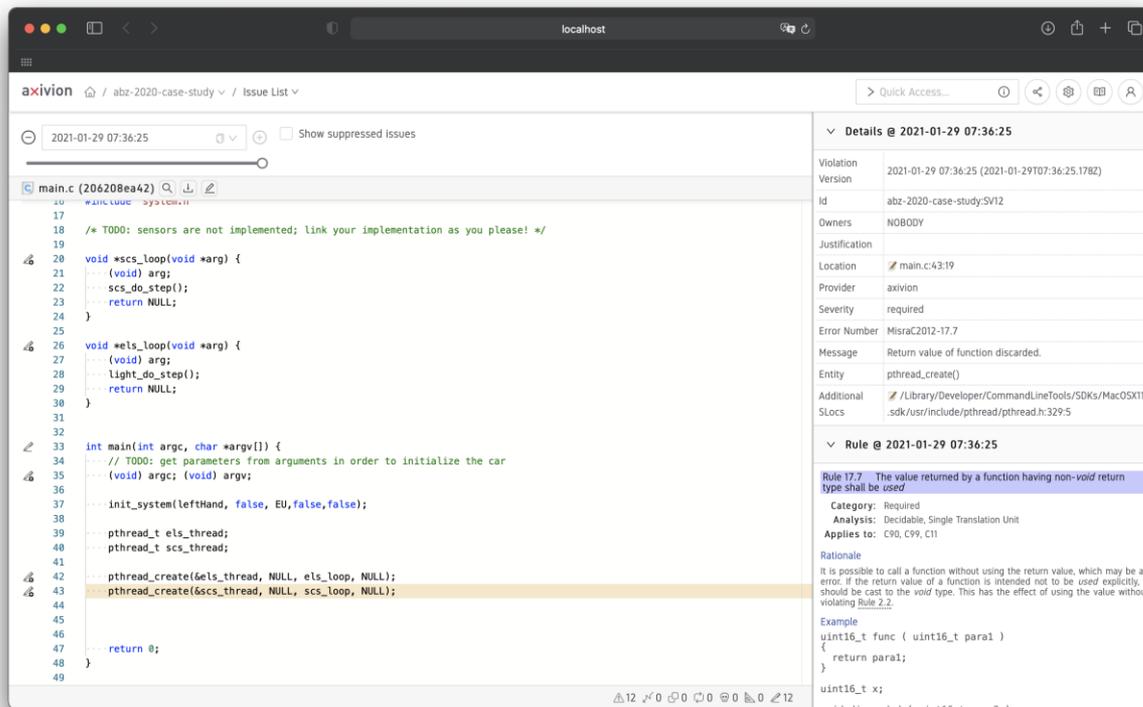
- Broadly speaking: avoid code execution, try to infer properties from the source code
- Many different techniques under one umbrella:
  - Style checking or linting
  - Data flow and pointer-based analyses
  - Abstract interpretation
  - Symbolic techniques
  - ....
- Comes at a price: over- and under-approximations and resulting false positives / negatives



The screenshot shows the Axivion web interface for a project named 'abz-2020-case-study'. The 'Issue List' view displays 17 issues. The interface includes a search bar, a date range filter (2021-01-29 07:36:25), and a table of issues with columns for Id, State, Error Number, Message, Entity, Path, Line, Provider, Severity, and Owners.

Id	State	Error Number	Message	Entity	Path	Line	Provider	Severity	Owners
SV1	added	MisraC2012-8.5	Function declared in more than one f...	get_key_status()	common.h   commo...	63	axivion	required	NOBODY
SV2	added	MisraC2012-8.5	Function declared in more than one f...	get_engine_status()	common.h   commo...	65	axivion	required	NOBODY
SV3	added	MisraC2012-8.5	Function declared in more than one f...	get_brake_pedal_d...	common.h   commo...	67	axivion	required	NOBODY
SV4	added	MisraC2012-8.5	Function declared in more than one f...	get_current_speed()	sensors.h   cruise-c...	26	axivion	required	NOBODY
SV5	added	MisraC2012-1.1	You have to compile with option --c9...	main.c	main.c	1	axivion	required	NOBODY
SV6	added	MisraC2012-8.4	Missing declaration for function defin...	scs_loop()	main.c	20	axivion	required	NOBODY
SV7	added	MisraC2012-8.4	Missing declaration for function defin...	e_ls_loop()	main.c	26	axivion	required	NOBODY
SV8	added	MisraC2012-8.13	Parameter can be declared as pointe...	arg	main.c	20	axivion	advisory	NOBODY
SV9	added	MisraC2012-8.13	Parameter can be declared as pointe...	arg	main.c	26	axivion	advisory	NOBODY
SV10	added	MisraC2012-8.13	Parameter can be declared as pointe...	argv	main.c	33	axivion	advisory	NOBODY
SV11	added	MisraC2012-17.7	Return value of function discarded.	pthread_create()	main.c	42	axivion	required	NOBODY
SV12	added	MisraC2012-17.7	Return value of function discarded.	pthread_create()	main.c	43	axivion	required	NOBODY
SV13	added	MisraC2012Directive-4.7	Integral return value (possibly error c...	pthread_create()	main.c	42	axivion	required	NOBODY

Total 17 issues < 1 > 50 / page



The screenshot shows the Axivion static analysis tool interface. The main window displays a C source file named `main.c` with the following code:

```

17
18 /* TODO: sensors are not implemented; link your implementation as you please! */
19
20 void *scs_loop(void *arg) {
21     (void) arg;
22     scs_do_step();
23     return NULL;
24 }
25
26 void *els_loop(void *arg) {
27     (void) arg;
28     light_do_step();
29     return NULL;
30 }
31
32
33 int main(int argc, char *argv[]) {
34     // TODO: get parameters from arguments in order to initialize the car
35     (void) argc; (void) argv;
36
37     init_system(leftHand, false, EU, false, false);
38
39     pthread_t els_thread;
40     pthread_t scs_thread;
41
42     pthread_create(&els_thread, NULL, els_loop, NULL);
43     pthread_create(&scs_thread, NULL, scs_loop, NULL);
44
45
46
47     return 0;
48
49
    
```

The issue is highlighted on line 43, where `pthread_create` is called with `NULL` for the return value. The details panel on the right shows the following information:

Details @ 2021-01-29 07:36:25	
Violation Version	2021-01-29 07:36:25 (2021-01-29T07:36:25.178Z)
Id	abz-2020-case-study-SV12
Owners	NOBODY
Justification	
Location	main.c:43:19
Provider	axivion
Severity	required
Error Number	MisraC2012-17.7
Message	Return value of function discarded.
Entity	pthread_create()
Additional SLocs	/Library/Developer/CommandLineTools/SDKs/MacOSX11.1.sdk/usr/include/pthread/pthread.h:329:5
Rule @ 2021-01-29 07:36:25	
<b>Rule 17.7. The value returned by a function having non-void return type shall be used.</b>	
Category:	Required
Analysis:	Decidable, Single Translation Unit
Applies to:	C90, C99, C11
<b>Rationale</b>	
It is possible to call a function without using the return value, which may be an error. If the return value of a function is intended not to be used explicitly, it should be cast to the void type. This has the effect of using the value without violating Rule 2.2.	
<b>Example</b>	
<pre> uint16_t func ( uint16_t para1 ) {     return para1; }  uint16_t x; void discarded_f (uint16_t para2)         </pre>	

- Not an out-of-the-box experience
- Needs customization and analyses tailored to the use case
- But can be realized on top of existing analysis frameworks
- Could be done for requirements such as “After engine start, there is no previous desired speed. The valid values for desired speed are from 1 km/h to 200 km/h.”

- Very helpful to ensure MISRA C2012 is adhered to
- Very helpful to uncover programming errors and security issues
  - Null pointer dereferences
  - Division by zero
  - Bad practices
  - ...
- Many things can be checked out of the box without tweaking
- Can sometimes be used for functional requirements, but that involves customizations

- Broadly speaking: show correctness of system with mathematical rigor
- Translate system into some mathematical / logical representation
- Use (semi-)automatic or manual proof techniques to prove properties
- Very high effort and skill needed

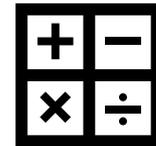
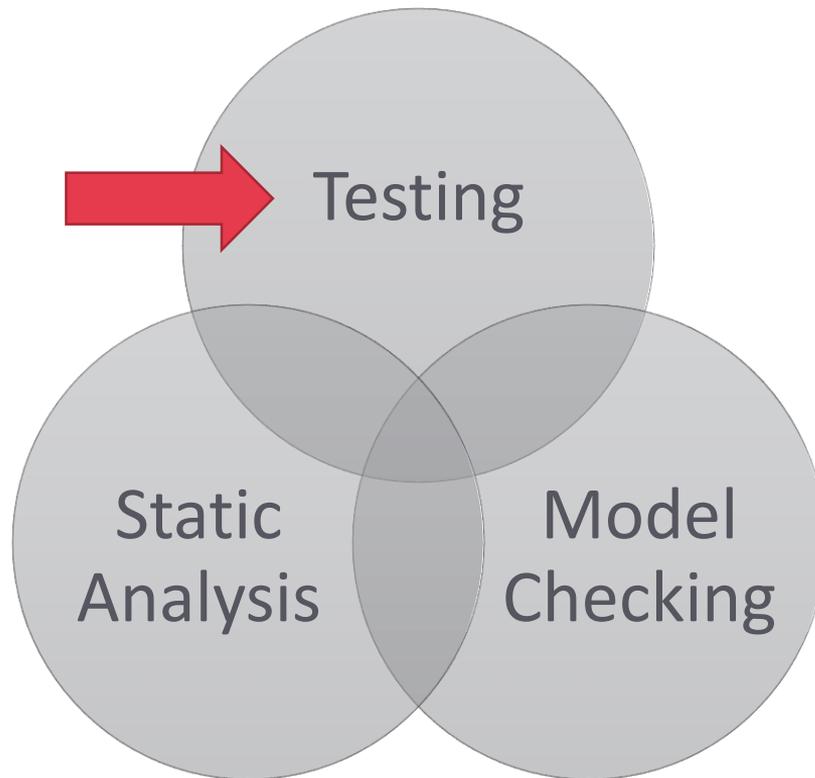
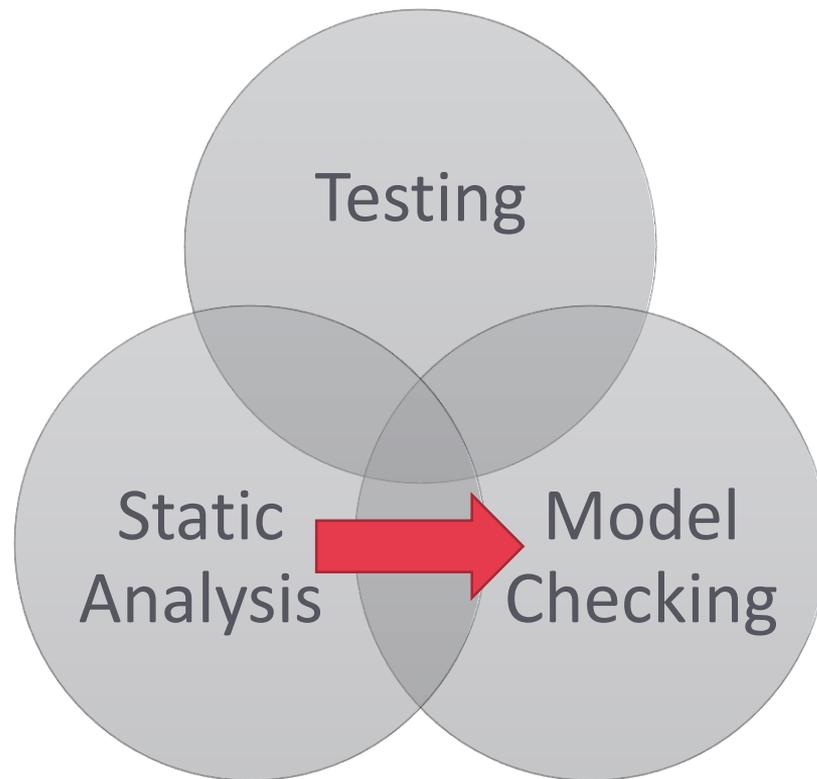
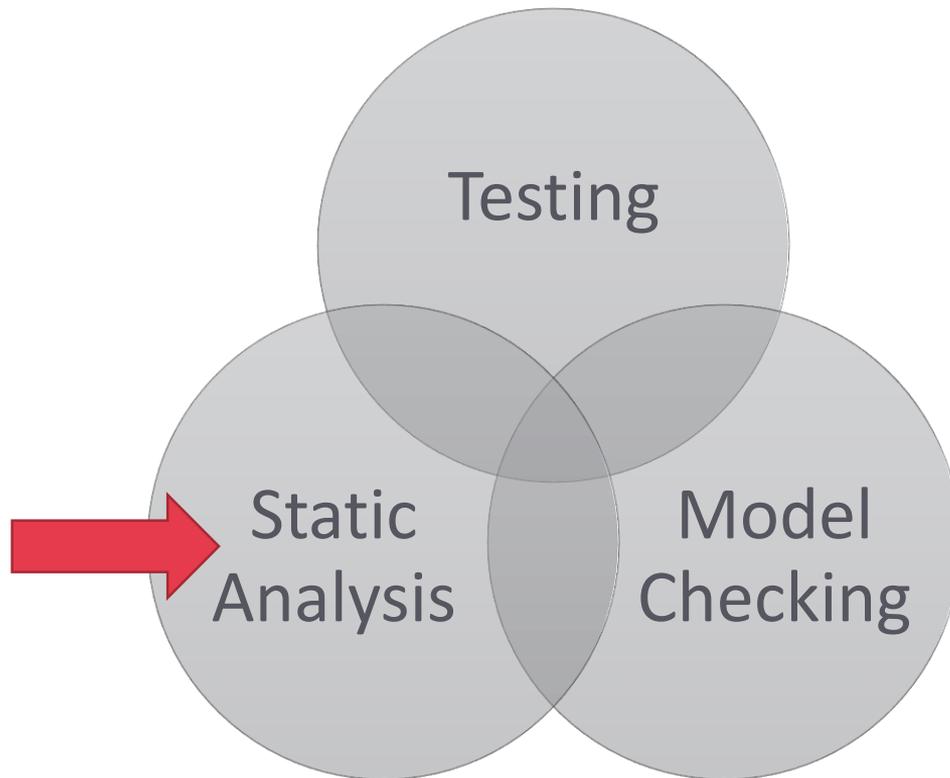


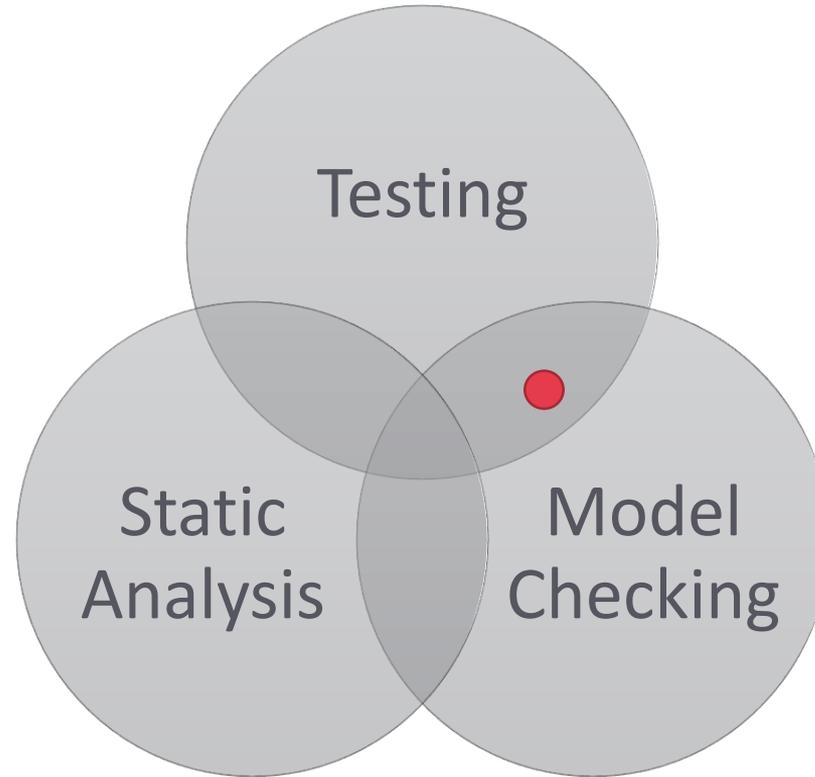


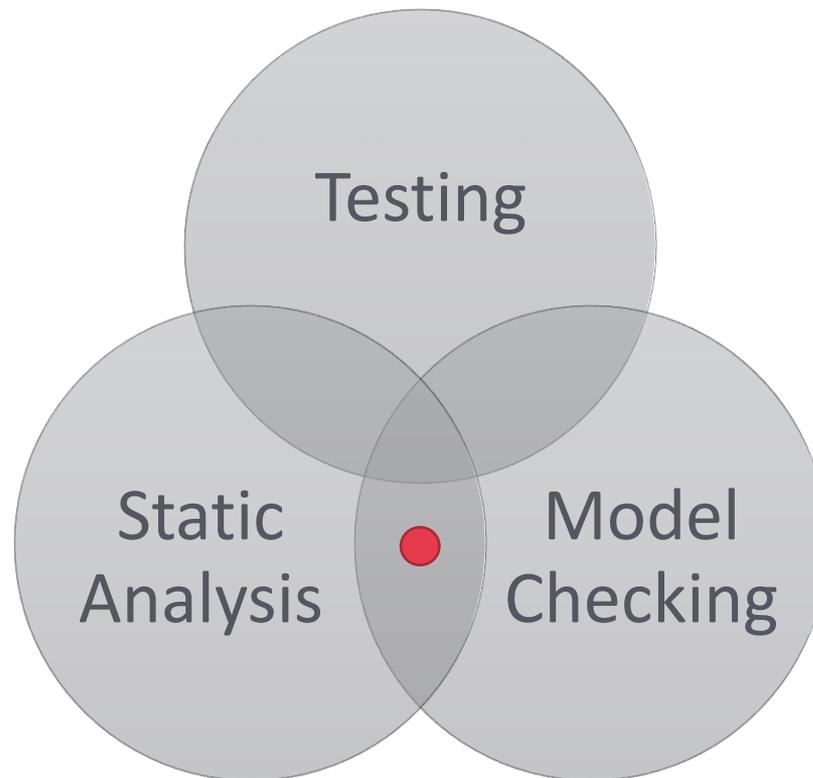
Image by Pline under CC BY-SA 3.0

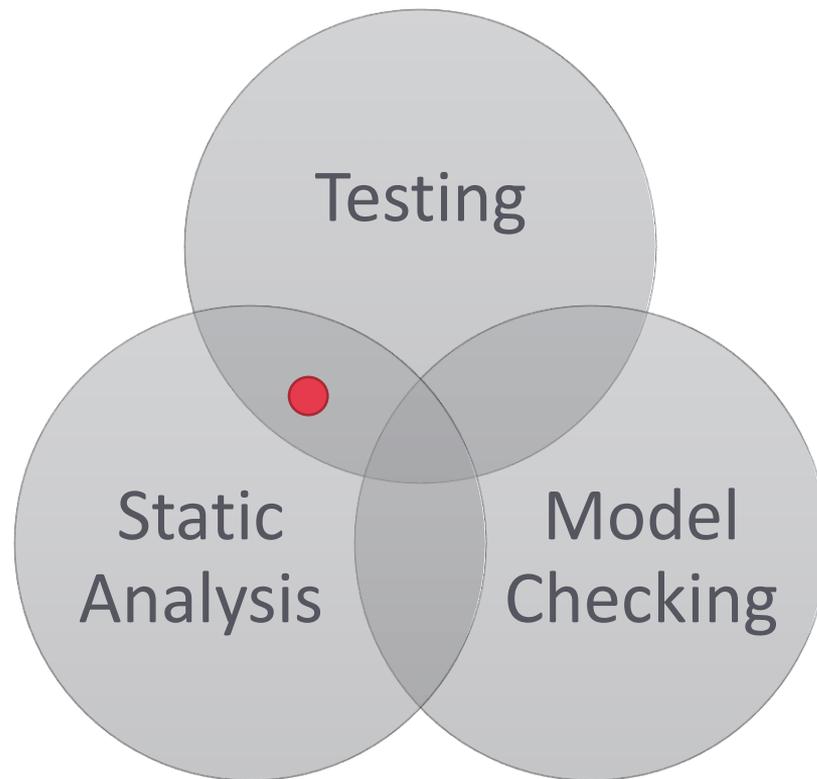


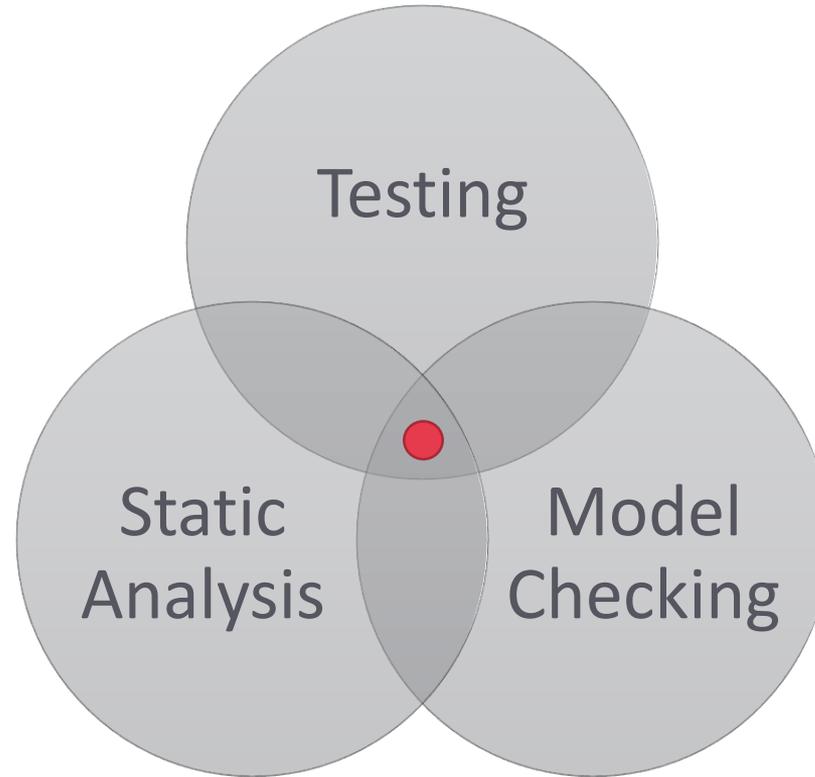












- Use whatever you can to ensure safety and security
- Techniques alone are useful ...
- ... but upcoming combinations might be even better.

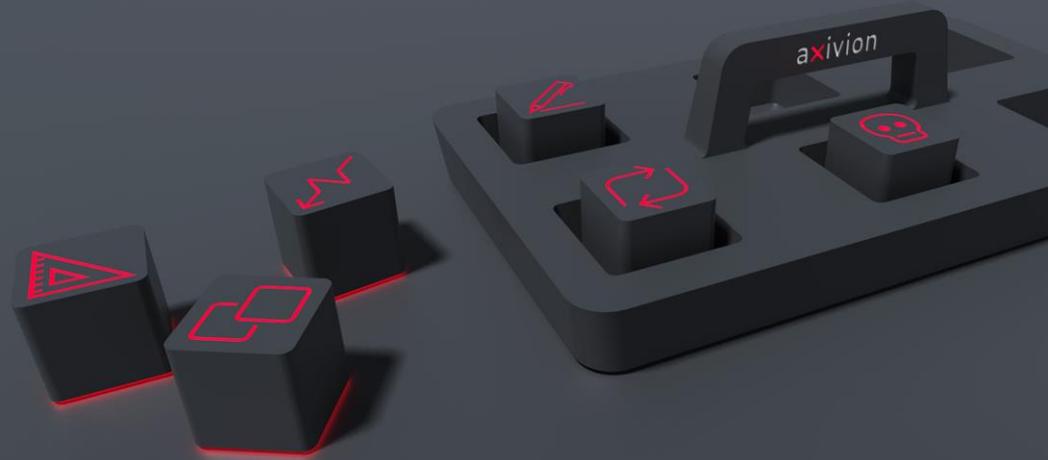
Stay tuned for what we come up with!



Thank you for your attention!

Contact:  
Sebastian Krings  
Axivion GmbH  
Nobelstraße 15  
70569 Stuttgart

Tel: +49 711 6204378-78  
E-Mail: [krings@axivion.com](mailto:krings@axivion.com)  
[www.axivion.com](http://www.axivion.com)



**axivion**  
stopping software erosion